

On the Application of Godunov-type Schemes to Conservation Laws Arising from the Equations of Nonlinear Acoustics*

Ivan Christov¹ C. I. Christov² P. M. Jordan³

¹Department of Mathematics, Texas A&M University, College Station, USA

²Department of Mathematics, University of Louisiana at Lafayette, USA

³Code 7181, Naval Research Laboratory, Stennis Space Center, USA

Special Session on Numerical Methods for Hyperbolic Problems,
6th International Conference on Numerical Methods and Applications,
Borovets, Bulgaria
August 20, 2006



*This research was supported, in part, by ONR/NRL funding.

- Motivation:
 - Acoustics is *not* just the study of linearized equations!
 - There are many weakly-nonlinear models. How are they all related? Which are “better”?
 - Numerical studies of the equations of nonlinear acoustics are scarce.
- The “classical” equations of nonlinear acoustic:
 - Westervelt (1963) derived a nonlinear wave equation for the pressure of highly-directional acoustic transmitters by ignoring the viscous terms in Lighthill's (1952) turbulence stress tensor for the acoustic field.
 - Kuznetsov (1971) expanding the barotropic equation of state of an ideal gas in a power series.
- Outline of the talk:
 - 1 Physical setup, assumptions and the equations of motion.
 - 2 Weakly-nonlinear approximations.
 - 3 Some analytical results for a BVP.
 - 4 Construction of “artificial” conservation laws.
 - 5 Comparison of the models before and after shock-formation.



The Big Picture

- Motivation:
 - Acoustics is *not* just the study of linearized equations!
 - There are many weakly-nonlinear models. How are they all related? Which are “better”?
 - Numerical studies of the equations of nonlinear acoustics are scarce.
- The “classical” equations of nonlinear acoustic:
 - Westervelt (1963) derived a nonlinear wave equation for the pressure of highly-directional acoustic transmitters by ignoring the viscous terms in Lighthill’s (1952) turbulence stress tensor for the acoustic field.
 - Kuznetsov (1971) expanding the barotropic equation of state of an ideal gas in a power series.
- Outline of the talk:
 - 1 Physical setup, assumptions and the equations of motion.
 - 2 Weakly-nonlinear approximations.
 - 3 Some analytical results for a BVP.
 - 4 Construction of “artificial” conservation laws.
 - 5 Comparison of the models before and after shock-formation.



The Big Picture

- Motivation:
 - Acoustics is *not* just the study of linearized equations!
 - There are many weakly-nonlinear models. How are they all related? Which are “better”?
 - Numerical studies of the equations of nonlinear acoustics are scarce.
- The “classical” equations of nonlinear acoustic:
 - Westervelt (1963) derived a nonlinear wave equation for the pressure of highly-directional acoustic transmitters by ignoring the viscous terms in Lighthill’s (1952) turbulence stress tensor for the acoustic field.
 - Kuznetsov (1971) expanding the barotropic equation of state of an ideal gas in a power series.
- Outline of the talk:
 - ① Physical setup, assumptions and the equations of motion.
 - ② Weakly-nonlinear approximations.
 - ③ Some analytical results for a BVP.
 - ④ Construction of “artificial” conservation laws.
 - ⑤ Comparison of the models before and after shock-formation.



Governing Equations of Motion

- General assumptions and setup:
 - ① The fluid is lossless (\equiv inviscid) and compressible.
 - ② The fluid is a perfect (\equiv thermally and calorically ideal) barotropic gas.
 - ③ Equilibrium (\equiv constant) initial conditions.
 - ④ Homentropic flow — i.e., the material derivative *and* gradient of the entropy vanish everywhere.
 - ⑤ 1D flow along the x axis, inflow boundary at $x = 0$.
 - ⑥ Signaling boundary conditions: a “pulse” of finite duration is introduced into either the density/pressure or velocity field at $x = 0$.
- Putting all this together results in the **Euler equations**, which can be written as a (nondimensionalized) conservation law:

$$\left(\begin{array}{c} \rho \\ \rho u \end{array} \right)_t + \left(\begin{array}{c} \epsilon \rho u \\ \epsilon \rho u^2 + \epsilon^{-1} \rho^\gamma / \gamma \end{array} \right)_x = 0,$$

where $(0 <) \epsilon \equiv u_0/c_0$ is the Mach number.



Governing Equations of Motion

- General assumptions and setup:
 - ① The fluid is lossless (\equiv inviscid) and compressible.
 - ② The fluid is a perfect (\equiv thermally and calorically ideal) barotropic gas.
 - ③ Equilibrium (\equiv constant) initial conditions.
 - ④ Homentropic flow — i.e., the material derivative *and* gradient of the entropy vanish everywhere.
 - ⑤ 1D flow along the x axis, inflow boundary at $x = 0$.
 - ⑥ Signaling boundary conditions: a “pulse” of finite duration is introduced into either the density/pressure or velocity field at $x = 0$.
- Putting all this together results in the **Euler equations**, which can be written as a (nondimensionalized) conservation law:

$$\left(\begin{array}{c} \rho \\ \rho u \end{array} \right)_t + \left(\begin{array}{c} \epsilon \rho u \\ \epsilon \rho u^2 + \epsilon^{-1} \rho^\gamma / \gamma \end{array} \right)_x = 0,$$

where $(0 <) \epsilon \equiv u_0/c_0$ is the Mach number.



Weakly-Nonlinear Approximations

- Let $\phi(x, t)$ be the acoustic potential, i.e. $\nabla\phi = (u(x, t), 0, 0)$.
- The Euler equations admit the following potential formulation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = \frac{1}{2}\epsilon^2(\gamma + 1)(\phi_x)^2\phi_{xx}.$$

- One might consider the naïve weakly-nonlinear approximation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = 0.$$

- Or the inviscid version of Kuznetsov's equation:

$$\phi_{xx} - [1 + \epsilon(\gamma - 1)\phi_t]\phi_{tt} = 2\epsilon\phi_x\phi_{xt}.$$

- Or, perhaps, even Lighthill & Westervelt's simplification:

$$\phi_{xx} - [1 + \epsilon(\gamma + 1)\phi_t]\phi_{tt} = 0.$$



Weakly-Nonlinear Approximations

- Let $\phi(x, t)$ be the acoustic potential, i.e. $\nabla\phi = (u(x, t), 0, 0)$.
- The Euler equations admit the following potential formulation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = \frac{1}{2}\epsilon^2(\gamma + 1)(\phi_x)^2\phi_{xx}.$$

- One might consider the naïve weakly-nonlinear approximation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = 0.$$

- Or the inviscid version of Kuznetsov's equation:

$$\phi_{xx} - [1 + \epsilon(\gamma - 1)\phi_t]\phi_{tt} = 2\epsilon\phi_x\phi_{xt}.$$

- Or, perhaps, even Lighthill & Westervelt's simplification:

$$\phi_{xx} - [1 + \epsilon(\gamma + 1)\phi_t]\phi_{tt} = 0.$$



Weakly-Nonlinear Approximations

- Let $\phi(x, t)$ be the acoustic potential, i.e. $\nabla\phi = (u(x, t), 0, 0)$.
- The Euler equations admit the following potential formulation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = \frac{1}{2}\epsilon^2(\gamma + 1)(\phi_x)^2\phi_{xx}.$$

- One might consider the naïve weakly-nonlinear approximation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = 0.$$

- Or the inviscid version of Kuznetsov's equation:

$$\phi_{xx} - [1 + \epsilon(\gamma - 1)\phi_t]\phi_{tt} = 2\epsilon\phi_x\phi_{xt}.$$

- Or, perhaps, even Lighthill & Westervelt's simplification:

$$\phi_{xx} - [1 + \epsilon(\gamma + 1)\phi_t]\phi_{tt} = 0.$$



Weakly-Nonlinear Approximations

- Let $\phi(x, t)$ be the acoustic potential, i.e. $\nabla\phi = (u(x, t), 0, 0)$.
- The Euler equations admit the following potential formulation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = \frac{1}{2}\epsilon^2(\gamma + 1)(\phi_x)^2\phi_{xx}.$$

- One might consider the naïve weakly-nonlinear approximation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = 0.$$

- Or the inviscid version of Kuznetsov's equation:

$$\phi_{xx} - [1 + \epsilon(\gamma - 1)\phi_t]\phi_{tt} = 2\epsilon\phi_x\phi_{xt}.$$

- Or, perhaps, even Lighthill & Westervelt's simplification:

$$\phi_{xx} - [1 + \epsilon(\gamma + 1)\phi_t]\phi_{tt} = 0.$$



Weakly-Nonlinear Approximations

- Let $\phi(x, t)$ be the acoustic potential, i.e. $\nabla\phi = (u(x, t), 0, 0)$.
- The Euler equations admit the following potential formulation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = \frac{1}{2}\epsilon^2(\gamma + 1)(\phi_x)^2\phi_{xx}.$$

- One might consider the naïve weakly-nonlinear approximation:

$$[1 - \epsilon(\gamma - 1)\phi_t]\phi_{xx} - 2\epsilon\phi_x\phi_{tx} - \phi_{tt} = 0.$$

- Or the inviscid version of Kuznetsov's equation:

$$\phi_{xx} - [1 + \epsilon(\gamma - 1)\phi_t]\phi_{tt} = 2\epsilon\phi_x\phi_{xt}.$$

- Or, perhaps, even Lighthill & Westervelt's simplification:

$$\phi_{xx} - [1 + \epsilon(\gamma + 1)\phi_t]\phi_{tt} = 0.$$



Acceleration Wave Analysis

- An *acceleration wave* is a jump discontinuity in at least one of the derivatives of the primitive variable (e.g., ρ).
- The basic idea: apply the method of characteristics at the *wavefront* and derive an expression for the amplitude of the jump as a function of time.
- *Blow-up* of the acceleration wave (\equiv the jump amplitude $\rightarrow \infty$) means a shock formed in the respective primitive variable.
- Pros: gives some theoretical results, which can be confirmed numerically, and can be used in evaluating the models.
- Cons: acceleration wave analysis ignores all other effects that lead to shock-formation (e.g., nonlinear steepening).
- For all of the equations and the BVP considered here the **blow-up time is the same**: $t_\infty = 2c_0 / \{(\gamma + 1)[u_t]_{t=0}\}$.



Acceleration Wave Analysis

- An *acceleration wave* is a jump discontinuity in at least one of the derivatives of the primitive variable (e.g., ρ).
- The basic idea: apply the method of characteristics at the *wavefront* and derive an expression for the amplitude of the jump as a function of time.
- *Blow-up* of the acceleration wave (\equiv the jump amplitude $\rightarrow \infty$) means a shock formed in the respective primitive variable.
- Pros: gives some theoretical results, which can be confirmed numerically, and can be used in evaluating the models.
- Cons: acceleration wave analysis ignores all other effects that lead to shock-formation (e.g., nonlinear steepening).
- For all of the equations and the BVP considered here the **blow-up time is the same**: $t_\infty = 2c_0 / \{(\gamma + 1)[u_t]_{t=0}\}$.



Acceleration Wave Analysis

- An *acceleration wave* is a jump discontinuity in at least one of the derivatives of the primitive variable (e.g., ρ).
- The basic idea: apply the method of characteristics at the *wavefront* and derive an expression for the amplitude of the jump as a function of time.
- *Blow-up* of the acceleration wave (\equiv the jump amplitude $\rightarrow \infty$) means a shock formed in the respective primitive variable.
- Pros: gives some theoretical results, which can be confirmed numerically, and can be used in evaluating the models.
- Cons: acceleration wave analysis ignores all other effects that lead to shock-formation (e.g., nonlinear steepening).
- For all of the equations and the BVP considered here the **blow-up time is the same**: $t_\infty = 2c_0 / \{(\gamma + 1)[u_t]_{t=0}\}$.



Acceleration Wave Analysis

- An *acceleration wave* is a jump discontinuity in at least one of the derivatives of the primitive variable (e.g., ρ).
- The basic idea: apply the method of characteristics at the *wavefront* and derive an expression for the amplitude of the jump as a function of time.
- *Blow-up* of the acceleration wave (\equiv the jump amplitude $\rightarrow \infty$) means a shock formed in the respective primitive variable.
- Pros: gives some theoretical results, which can be confirmed numerically, and can be used in evaluating the models.
- Cons: acceleration wave analysis ignores all other effects that lead to shock-formation (e.g., nonlinear steepening).
- For all of the equations and the BVP considered here the **blow-up time is the same**: $t_\infty = 2c_0 / \{(\gamma + 1)[u_t]_{t=0}\}$.



Acceleration Wave Analysis

- An *acceleration wave* is a jump discontinuity in at least one of the derivatives of the primitive variable (e.g., ρ).
- The basic idea: apply the method of characteristics at the *wavefront* and derive an expression for the amplitude of the jump as a function of time.
- *Blow-up* of the acceleration wave (\equiv the jump amplitude $\rightarrow \infty$) means a shock formed in the respective primitive variable.
- Pros: gives some theoretical results, which can be confirmed numerically, and can be used in evaluating the models.
- Cons: acceleration wave analysis ignores all other effects that lead to shock-formation (e.g., nonlinear steepening).
- For all of the equations and the BVP considered here the **blow-up time is the same**: $t_\infty = 2c_0 / \{(\gamma + 1)[u_t]_{t=0}\}$.



Acceleration Wave Analysis

- An *acceleration wave* is a jump discontinuity in at least one of the derivatives of the primitive variable (e.g., ρ).
- The basic idea: apply the method of characteristics at the *wavefront* and derive an expression for the amplitude of the jump as a function of time.
- *Blow-up* of the acceleration wave (\equiv the jump amplitude $\rightarrow \infty$) means a shock formed in the respective primitive variable.
- Pros: gives some theoretical results, which can be confirmed numerically, and can be used in evaluating the models.
- Cons: acceleration wave analysis ignores all other effects that lead to shock-formation (e.g., nonlinear steepening).
- For all of the equations and the BVP considered here the **blow-up time is the same**: $t_\infty = 2c_0 / \{(\gamma + 1)[u_t]_{t=0}\}$.



Potential Equation \rightarrow System of Conservation Laws

- From our assumptions, we know that $\phi_x = u$ and $\phi_t = (1 - \rho)/\epsilon$.
- So the (potential) LWE can be rewritten as

$$\begin{aligned} [(\gamma + 2)\rho - \frac{1}{2}(\gamma + 1)\rho^2]_t + \epsilon u_x &= 0, \\ u_t + \epsilon^{-1}\rho_x &= 0. \end{aligned}$$

- But this is not yet a conservation law! So, let

$$\begin{aligned} \tilde{\rho} &\stackrel{\text{def}}{=} (\gamma + 2)\rho - \frac{1}{2}(\gamma + 1)\rho^2, \text{ s.t.} \\ \rho &= \frac{1}{\gamma + 1} \left[\gamma + 2 \mp \sqrt{(\gamma + 2)^2 - 2(\gamma + 1)\tilde{\rho}} \right]. \end{aligned}$$

- Finally, we get

$$\begin{pmatrix} \tilde{\rho} \\ u \end{pmatrix}_t + \begin{pmatrix} \epsilon u \\ -[\epsilon(\gamma + 1)]^{-1} \sqrt{(\gamma + 2)^2 - 2(\gamma + 1)\tilde{\rho}} \end{pmatrix}_x = 0.$$

- The other two weakly-nonlinear equations can be converted into conservation laws in the same manner.



Potential Equation \rightarrow System of Conservation Laws

- From our assumptions, we know that $\phi_x = u$ and $\phi_t = (1 - \rho)/\epsilon$.
- So the (potential) LWE can be rewritten as

$$\begin{aligned} [(\gamma + 2)\rho - \frac{1}{2}(\gamma + 1)\rho^2]_t + \epsilon u_x &= 0, \\ u_t + \epsilon^{-1}\rho_x &= 0. \end{aligned}$$

- But this is not yet a conservation law! So, let

$$\begin{aligned} \tilde{\rho} &\stackrel{\text{def}}{=} (\gamma + 2)\rho - \frac{1}{2}(\gamma + 1)\rho^2, \text{ s.t.} \\ \rho &= \frac{1}{\gamma + 1} \left[\gamma + 2 \mp \sqrt{(\gamma + 2)^2 - 2(\gamma + 1)\tilde{\rho}} \right]. \end{aligned}$$

- Finally, we get

$$\begin{pmatrix} \tilde{\rho} \\ u \end{pmatrix}_t + \begin{pmatrix} \epsilon u \\ -[\epsilon(\gamma + 1)]^{-1} \sqrt{(\gamma + 2)^2 - 2(\gamma + 1)\tilde{\rho}} \end{pmatrix}_x = 0.$$

- The other two weakly-nonlinear equations can be converted into conservation laws in the same manner.



Potential Equation \rightarrow System of Conservation Laws

- From our assumptions, we know that $\phi_x = u$ and $\phi_t = (1 - \rho)/\epsilon$.
- So the (potential) LWE can be rewritten as

$$\begin{aligned} [(\gamma + 2)\rho - \frac{1}{2}(\gamma + 1)\rho^2]_t + \epsilon u_x &= 0, \\ u_t + \epsilon^{-1}\rho_x &= 0. \end{aligned}$$

- But this is not yet a conservation law! So, let

$$\begin{aligned} \tilde{\rho} &\stackrel{\text{def}}{=} (\gamma + 2)\rho - \frac{1}{2}(\gamma + 1)\rho^2, \text{ s.t.} \\ \rho &= \frac{1}{\gamma + 1} \left[\gamma + 2 \mp \sqrt{(\gamma + 2)^2 - 2(\gamma + 1)\tilde{\rho}} \right]. \end{aligned}$$

- Finally, we get

$$\begin{pmatrix} \tilde{\rho} \\ u \end{pmatrix}_t + \begin{pmatrix} \epsilon u \\ -[\epsilon(\gamma + 1)]^{-1} \sqrt{(\gamma + 2)^2 - 2(\gamma + 1)\tilde{\rho}} \end{pmatrix}_x = 0.$$

- The other two weakly-nonlinear equations can be converted into conservation laws in the same manner.



Potential Equation \rightarrow System of Conservation Laws

- From our assumptions, we know that $\phi_x = u$ and $\phi_t = (1 - \rho)/\epsilon$.
- So the (potential) LWE can be rewritten as

$$\begin{aligned} [(\gamma + 2)\rho - \frac{1}{2}(\gamma + 1)\rho^2]_t + \epsilon u_x &= 0, \\ u_t + \epsilon^{-1}\rho_x &= 0. \end{aligned}$$

- But this is not yet a conservation law! So, let

$$\begin{aligned} \tilde{\rho} &\stackrel{\text{def}}{=} (\gamma + 2)\rho - \frac{1}{2}(\gamma + 1)\rho^2, \text{ s.t.} \\ \rho &= \frac{1}{\gamma + 1} \left[\gamma + 2 \mp \sqrt{(\gamma + 2)^2 - 2(\gamma + 1)\tilde{\rho}} \right]. \end{aligned}$$

- Finally, we get

$$\begin{pmatrix} \tilde{\rho} \\ u \end{pmatrix}_t + \begin{pmatrix} \epsilon u \\ -[\epsilon(\gamma + 1)]^{-1} \sqrt{(\gamma + 2)^2 - 2(\gamma + 1)\tilde{\rho}} \end{pmatrix}_x = 0.$$

- The other two weakly-nonlinear equations can be converted into conservation laws in the same manner.



The MUSCL–Hancock Scheme

- Consider the generic 1D hyperbolic system of conservation laws:

$$\mathbf{Q}_t + \mathbf{F}(\mathbf{Q})_x = 0.$$

- Introduce the conservative discretization:

$$\mathbf{Q}_i^{n+1} = \mathbf{Q}_i^n + \frac{\Delta t}{\Delta x} \left(\mathbf{F}_{i-\frac{1}{2}}^n - \mathbf{F}_{i+\frac{1}{2}}^n \right).$$

- Perform a (linear) MUSCL extrapolation of the cell-interface values:

$$\mathbf{Q}_i^{L,R} = \mathbf{Q}_i \mp \frac{1}{2} \min\text{mod}(\mathbf{Q}_i - \mathbf{Q}_{i-1}, \mathbf{Q}_{i+1} - \mathbf{Q}_i).$$

- Use predictor for the cell-interface temporal midvalues:

$$\bar{\mathbf{Q}}_i^{L,R} = \mathbf{Q}_i^{L,R} + \frac{1}{2} \frac{\Delta t}{\Delta x} \left[\mathbf{F}(\mathbf{Q}_i^L) - \mathbf{F}(\mathbf{Q}_i^R) \right].$$

- Finally, use $\bar{\mathbf{Q}}_i^R$ and $\bar{\mathbf{Q}}_{i+1}^L$ to set up a generalized Riemann problem at each cell interface $x_{i+\frac{1}{2}}$, and the Harten–Lax–van Leer approximate Riemann solver to obtain the flux $\mathbf{F}_{i+\frac{1}{2}}^n$ ($-1 \leq i \leq N-1$).



The MUSCL–Hancock Scheme

- Consider the generic 1D hyperbolic system of conservation laws:

$$\mathbf{Q}_t + \mathbf{F}(\mathbf{Q})_x = 0.$$

- Introduce the conservative discretization:

$$\mathbf{Q}_i^{n+1} = \mathbf{Q}_i^n + \frac{\Delta t}{\Delta x} \left(\mathbf{F}_{i-\frac{1}{2}}^n - \mathbf{F}_{i+\frac{1}{2}}^n \right).$$

- Perform a (linear) MUSCL extrapolation of the cell-interface values:

$$\mathbf{Q}_i^{L,R} = \mathbf{Q}_i \mp \frac{1}{2} \min\text{mod}(\mathbf{Q}_i - \mathbf{Q}_{i-1}, \mathbf{Q}_{i+1} - \mathbf{Q}_i).$$

- Use predictor for the cell-interface temporal midvalues:

$$\bar{\mathbf{Q}}_i^{L,R} = \mathbf{Q}_i^{L,R} + \frac{1}{2} \frac{\Delta t}{\Delta x} \left[\mathbf{F}(\mathbf{Q}_i^L) - \mathbf{F}(\mathbf{Q}_i^R) \right].$$

- Finally, use $\bar{\mathbf{Q}}_i^R$ and $\bar{\mathbf{Q}}_{i+1}^L$ to set up a generalized Riemann problem at each cell interface $x_{i+\frac{1}{2}}$, and the Harten–Lax–van Leer approximate Riemann solver to obtain the flux $\mathbf{F}_{i+\frac{1}{2}}^n$ ($-1 \leq i \leq N-1$).



The MUSCL–Hancock Scheme

- Consider the generic 1D hyperbolic system of conservation laws:

$$\mathbf{Q}_t + \mathbf{F}(\mathbf{Q})_x = 0.$$

- Introduce the conservative discretization:

$$\mathbf{Q}_i^{n+1} = \mathbf{Q}_i^n + \frac{\Delta t}{\Delta x} \left(\mathbf{F}_{i-\frac{1}{2}}^n - \mathbf{F}_{i+\frac{1}{2}}^n \right).$$

- Perform a (linear) MUSCL extrapolation of the cell-interface values:

$$\mathbf{Q}_i^{L,R} = \mathbf{Q}_i \mp \frac{1}{2} \min\text{mod}(\mathbf{Q}_i - \mathbf{Q}_{i-1}, \mathbf{Q}_{i+1} - \mathbf{Q}_i).$$

- Use predictor for the cell-interface temporal midvalues:

$$\bar{\mathbf{Q}}_i^{L,R} = \mathbf{Q}_i^{L,R} + \frac{1}{2} \frac{\Delta t}{\Delta x} \left[\mathbf{F}(\mathbf{Q}_i^L) - \mathbf{F}(\mathbf{Q}_i^R) \right].$$

- Finally, use $\bar{\mathbf{Q}}_i^R$ and $\bar{\mathbf{Q}}_{i+1}^L$ to set up a generalized Riemann problem at each cell interface $x_{i+\frac{1}{2}}$, and the Harten–Lax–van Leer approximate Riemann solver to obtain the flux $\mathbf{F}_{i+\frac{1}{2}}^n$ ($-1 \leq i \leq N-1$).



The MUSCL–Hancock Scheme

- Consider the generic 1D hyperbolic system of conservation laws:

$$\mathbf{Q}_t + \mathbf{F}(\mathbf{Q})_x = 0.$$

- Introduce the conservative discretization:

$$\mathbf{Q}_i^{n+1} = \mathbf{Q}_i^n + \frac{\Delta t}{\Delta x} \left(\mathbf{F}_{i-\frac{1}{2}}^n - \mathbf{F}_{i+\frac{1}{2}}^n \right).$$

- Perform a (linear) MUSCL extrapolation of the cell-interface values:

$$\mathbf{Q}_i^{L,R} = \mathbf{Q}_i \mp \frac{1}{2} \min\text{mod}(\mathbf{Q}_i - \mathbf{Q}_{i-1}, \mathbf{Q}_{i+1} - \mathbf{Q}_i).$$

- Use predictor for the cell-interface temporal midvalues:

$$\bar{\mathbf{Q}}_i^{L,R} = \mathbf{Q}_i^{L,R} + \frac{1}{2} \frac{\Delta t}{\Delta x} \left[\mathbf{F}(\mathbf{Q}_i^L) - \mathbf{F}(\mathbf{Q}_i^R) \right].$$

- Finally, use $\bar{\mathbf{Q}}_i^R$ and $\bar{\mathbf{Q}}_{i+1}^L$ to set up a generalized Riemann problem at each cell interface $x_{i+\frac{1}{2}}$, and the Harten–Lax–van Leer approximate Riemann solver to obtain the flux $\mathbf{F}_{i+\frac{1}{2}}^n$ ($-1 \leq i \leq N-1$).



The MUSCL–Hancock Scheme

- Consider the generic 1D hyperbolic system of conservation laws:

$$\mathbf{Q}_t + \mathbf{F}(\mathbf{Q})_x = 0.$$

- Introduce the conservative discretization:

$$\mathbf{Q}_i^{n+1} = \mathbf{Q}_i^n + \frac{\Delta t}{\Delta x} \left(\mathbf{F}_{i-\frac{1}{2}}^n - \mathbf{F}_{i+\frac{1}{2}}^n \right).$$

- Perform a (linear) MUSCL extrapolation of the cell-interface values:

$$\mathbf{Q}_i^{L,R} = \mathbf{Q}_i \mp \frac{1}{2} \min\text{mod}(\mathbf{Q}_i - \mathbf{Q}_{i-1}, \mathbf{Q}_{i+1} - \mathbf{Q}_i).$$

- Use predictor for the cell-interface temporal midvalues:

$$\bar{\mathbf{Q}}_i^{L,R} = \mathbf{Q}_i^{L,R} + \frac{1}{2} \frac{\Delta t}{\Delta x} \left[\mathbf{F}(\mathbf{Q}_i^L) - \mathbf{F}(\mathbf{Q}_i^R) \right].$$

- Finally, use $\bar{\mathbf{Q}}_i^R$ and $\bar{\mathbf{Q}}_{i+1}^L$ to set up a generalized Riemann problem at each cell interface $x_{i+\frac{1}{2}}$, and the Harten–Lax–van Leer approximate Riemann solver to obtain the flux $\mathbf{F}_{i+\frac{1}{2}}^n$ ($-1 \leq i \leq N-1$).



Numerical Results for $t < t_\infty$

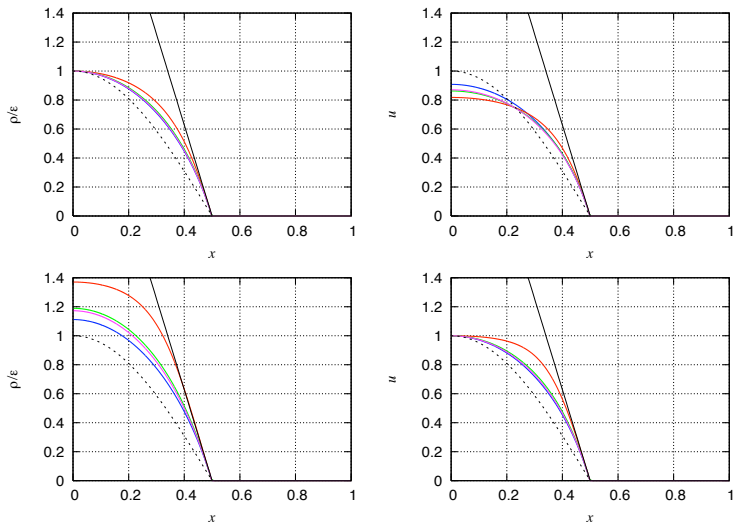


Figure: Top row: density BC; bottom row: velocity BC; $t = 0.5$.



Numerical Results for $t > t_\infty$

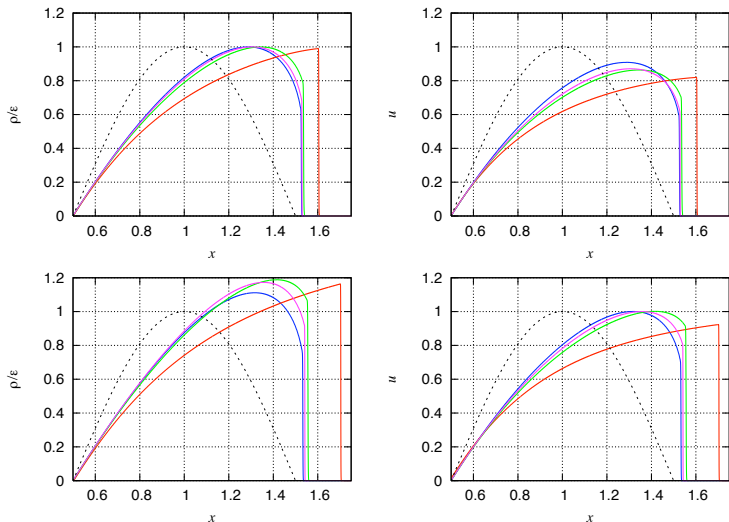


Figure: Top row: density BC; bottom row: velocity BC; $t = 1.5$.



Conclusions and Outlook

- So, what's a “good” weakly-nonlinear approximation? Well, it's hard to say ... no theoretical results but the numerics are illuminating.
- It is clear, however, that if one *must* use a weakly-nonlinear approximation, then the “naïve” one is superior to the “classical” ones.
- Black-box solver approach was crucial for the numerical simulations. The MUSCL–Hancock scheme with the HLL solver worked well, but a *central* scheme would be better (especially in 2D).
- Further theoretical work is needed for the BVP — use the method of characteristics beyond the wavefront and compute the time of shock-formation.



Conclusions and Outlook

- So, what's a “good” weakly-nonlinear approximation? Well, it's hard to say ... no theoretical results but the numerics are illuminating.
- It is clear, however, that if one *must* use a weakly-nonlinear approximation, then the “naïve” one is superior to the “classical” ones.
- Black-box solver approach was crucial for the numerical simulations. The MUSCL–Hancock scheme with the HLL solver worked well, but a *central* scheme would be better (especially in 2D).
- Further theoretical work is needed for the BVP — use the method of characteristics beyond the wavefront and compute the time of shock-formation.



Conclusions and Outlook

- So, what's a “good” weakly-nonlinear approximation? Well, it's hard to say ... no theoretical results but the numerics are illuminating.
- It is clear, however, that if one *must* use a weakly-nonlinear approximation, then the “naïve” one is superior to the “classical” ones.
- Black-box solver approach was crucial for the numerical simulations. The MUSCL–Hancock scheme with the HLL solver worked well, but a *central* scheme would be better (especially in 2D).
- Further theoretical work is needed for the BVP — use the method of characteristics beyond the wavefront and compute the time of shock-formation.



Conclusions and Outlook

- So, what's a “good” weakly-nonlinear approximation? Well, it's hard to say ... no theoretical results but the numerics are illuminating.
- It is clear, however, that if one *must* use a weakly-nonlinear approximation, then the “naïve” one is superior to the “classical” ones.
- Black-box solver approach was crucial for the numerical simulations. The MUSCL–Hancock scheme with the HLL solver worked well, but a *central* scheme would be better (especially in 2D).
- Further theoretical work is needed for the BVP — use the method of characteristics beyond the wavefront and compute the time of shock-formation.

